

## **The initial roadmap & draft declarations**

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## Workshop output

Document	Due date
Roadmap      draft version final version	02-10-2009 15-10-2009
Resolutions   consolidated	02-10-2009
Declarations   consolidated	02-10-2009
Workshop report	15-11-2009
Summary report in Episodes	TBD
Thematic issue of <i>Physics and Chemistry of the Earth</i>	TBD



## Resolutions

**Resolutions** from the  
Workshop on The Future of Satellite  
Gravimetry,  
12–13 April 2007, ESTEC; Noordwijk

### **The Future of Satellite Gravimetry**

Report from the  
Workshop on The Future of Satellite Gravimetry  
12-13 April 2007, ESTEC, Noordwijk, The Netherlands

Radboud Koop and Reiner Rummel (Eds.)



1

GRACE is demonstrating very successfully to provide monthly time series of changes in the Earth's gravity field. This adds a new – and very central – parameter set to the study of Global Change phenomena such as deglaciation in the large ice shields of Antarctica and Greenland or the variations of the global water cycle.

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## **Proposal:**

Statement on the value of GRACE and its impact in geosciences, including a non-exhaustive list of examples in diverse fields of application, but also current limitations.

→ B1, B5, B6

2

GOCE – to be launched 2008 – is expected to deliver the global static gravity field and geoid with unprecedented precision and spatial resolution. It will in particular serve as reference for global ocean circulation studies by altimetry.

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## **Proposal:**

Updated statement on the GOCE status, expected gain with respect to GRACE, and expected impact.

→ B1, B2, B5, B6

**3a**

In view of science achievements and the current performance of GRACE the participants of the workshop strongly support the idea of a GRACE follow-on mission based on the present configuration, with emphasis on the uninterrupted continuation of time series of global gravity changes. This should be short-term (Launch ~2011 TBD) priority one.

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## **Seed questions:**

- How can we support the initiative on the GRACE follow-on mission?

→ B1 – B6

**3b**

In parallel, investigations into the reduction of the aliasing problem offers even greater science benefits by increased spatial resolution and accuracy and should therefore have high priority.

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## **Seed questions:**

- What is the status of investigations related to the problems of aliasing and distortions, what are the conclusions?
- Have we significantly increased the insight into these problems since 2007?
- What are possible (and realistic) scenarios to solve/reduce these problems, and what is their expected qualification time?

→ B2, B3, B4

4

Medium term priority should be focused on higher precision and higher resolution in space and time. This step requires (1) the reduction of the current level of aliasing (of high frequency phenomena, in particular tides, into the time series), (2) the elimination of systematic distortions (caused by the peculiar non-isotropic sensitivity of a single pair low-low SST), and (3) the improvement of the separability of the observed geophysical signals.

Elements of a strategy in this direction are configuration flights, multi-satellite systems, improved data processing methodologies and improved and comprehensive Earth System modeling.

This will open the door to a more efficient use of improved sensor systems, such as optical ranging systems, quantum gravity sensors, and active angular and drag-free control.

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### **Seed questions:**

- What is the scientific progress since 2007?
- How large are the relative contributions of ...



4

Medium term priority should be focused on higher precision and higher resolution in space and time. This step requires (1) the reduction of the ...

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## **Seed questions:**

- What is the scientific progress since 2007?
- How large are the relative contributions of
  - sensor system (noise level, anisotropic error behaviour, ...)
  - inaccurate knowledge of background models
  - spectral and temporal aliasing
  - processing errors
  - supporting technologies (tracking systems, accelerometers, drag-free systems)
- Do we need a consistent Earth system model to fully exploit space gravity observations (role of hydrology, oceans, atmosphere; separability) ?
- How can we involve experts of supporting sciences more prominently in our discussion?

→ B1 – B6

5

The long term strategy should include the gravimetric use of advanced clocks (ground based and flying clocks), micro-satellite systems, and space-qualified quantum gravity sensors.

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### Seed questions:

- What is the status and scientific progress of those new technologies?
- Which of these technologies are not / less affected by the problems we are currently dealing with?

→ B2, B4

6

The participants of the workshop support the activities and developments towards a future satellite gravity mission.

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## Proposal:

- I hope we will find a majority for this statement!



→ all

7

The workshop results will be offered to national and international space agencies and other relevant institutions.

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## Proposal:

- We should also think about a dissemination strategy during this workshop.

→ B6

8

The initiative will be taken to set up an international steering/working group or platform to coordinate the future activities and actions in this field.

## Seed questions:

- Shall we take concrete steps to install such an international steering/working \_group?
- If yes, how can we organize it most efficiently?
- Which should be the institutional platform of such a working group, also for the purpose of legitimation?

Who is prepared and willing to join?



9

Links between the geodetic and Earth science community with the communities from fundamental physics will be strengthened and/or established.

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## **Evaluation:**

- This statement is answered positively by the list of participants of this workshop!

## Seed questions:

- Which additional statements are required for the new resolutions?
- TBD

→ all

## Roadmap

**Inventory** from the  
Workshop on The Future of Satellite  
Gravimetry,  
12–13 April 2007, ESTEC; Noordwijk

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## Accuracy requirements

- static

Table 3-1: Static gravity field, scientific requirements in preparation for GOCE, from: Rummel (2005).

Static gravity field, scientific requirements in preparation for GOCE				
Application		Accuracy		Spatial resolution
		Geoid [cm]	Gravity [mGal]	Half wavelength D [km]
Solid Earth	Lithosphere/upper mantle density		1-2	100
	Continental lithosphere  Sedimentary		1-2	50-100
	Basins rifts		1-2	20-100
	Tectonic motions		1-2	100-500
	Seismic hazards		1	100
	Ocean lithosphere/asthenosphere		0.5	100-200
Oceanography	Short scale	1-2		100
		0.2		200
	Basin scale	~0.1		1000
Ice sheets	Rock basement		1-5	50-100
	Ice vertical movements	2		100-1000
Geodesy	Levelling by GPS	1		100-1000
	Unified height system	1		100-20000
	INS		~1-5	100-1000
	Orbits		~1-3	100-1000
Sea level change	Many of the above applications, with their specific requirements, are relevant to studies of sea level change.			

- temporal

Table 3-2: Accuracy requirements.

Application	mm <sub>H2O</sub> /mon	mm <sub>H2O</sub> /yr	smoothing radius (km) $\geq 300$	Timescales and Notes
Hydrologic basin total water change	10	20 (10)	400	days to decades
Glacier mass loss		2 (1)	300	seasonal, interannual
Ice sheet mass loss		20 (5)	1,000	
Oceanic gyres spinup or down		4 (1)	700	interannual
Global Sea level rise: thermosteric / eustatic		1 (0.3)	5,000	seasonal, interannual
Glacial Isostatic Adjustment		0.5 (0.1)	1,000	5-10 years

## Candidate technology

- gravity sensors

Table 6-1: Gravity Sensors and Their Status of Development.

	Status	Expected qualification time*
Microwave interferometer	Flight proven (TRL9)	-
Inter-spacecraft Laser interferometer: Master-slave (2 lasers) Master+retro-reflector(1 laser)	Qualified prototype (TRL6) Breadboard (TRL4)	1-2 years 2-4 years
Gradiometer: Electro-static LTP Optical test mass readout Quantum	Flight qualified (TRL8) Launch in 2010 (TRL7) Breadboard (TRL3)	- 1 year 15 years
Cryogenic	Breadboard (TRL3)	undefined (unfit for mission)
Drag-free low-low SST: LTP Gravity Reference Sensor One-axis Ion Thrusters 5-DoF FEED Thrusters	Launch in 2009 (TRL7) Flight Proven (TRL 9) Launch in 2009 (TRL 5)	1 year - 3 years
Optical clock	Qualified prototype (TRL6)	15 years

- supporting technology

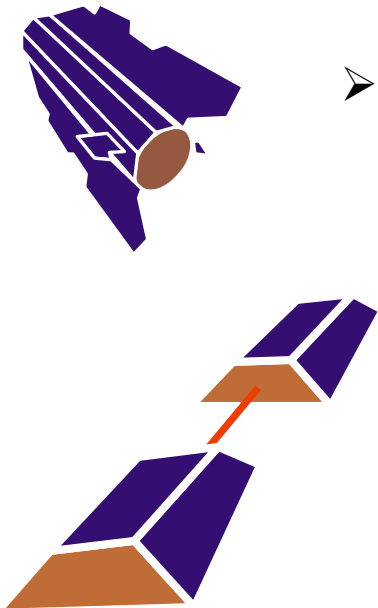
Table 6-2: Supporting Technology for Future Gravimetric Satellite Missions.

	Status	Expected qualification time
Tracking system: GPS GLONASS GALILEO	Flight proven (TRL9) Flight proven (TRL9) Prototype (TRL5)	- 1-2 years *
Electric propulsion: Ion engine (high thrust) FEED (low thrust)	Flight qualified (TRL8) Qualified prototype (TRL6)	- 2-4 years
Accelerometer $10^{-10} \text{ ms}^{-2}$ Accelerometer $10^{-12} \text{ ms}^{-2}$	Flight proven (TRL9)** Flight qualified (TRL8)**	- -
LISA/LTP inertial sensor $10^{-14} \text{ ms}^{-2}$	Launch in 2010 (TRL7)	1 year

## Roadmap: Key elements of matrix of mission concepts

### Gravity sensor / formation

- Mission (user) requirements
- Expected performance
- Pros & cons of mission concept
- Level of technological maturity (TRL)
- Expected qualification time
- Level of readiness of supporting science
- Remaining scientific challenges and expected solution time
- Complementarity with and need of other data sources
- Cost estimates
- Prioritization (→ baseline strategy)



## Wednesday

## Charge to the Breakout Sessions

09:00 – 10:40	<b>P1: Status, Requirements and Challenges</b>		
10:40 – 11:00	Coffee Break		
11:00 – 11:20	Introduction to Breakout Sessions		
11:20 – 12:40	<b>B1</b> <b>A306</b> Mission requirements	<b>B2</b> <b>BE01</b> Mission design	<b>B3</b> <b>A111</b> Data proc., modelling & interpret.
12:40 – 14:00	Lunch (buffet)		
14:00 – 15:40	<b>B1</b> <b>A306</b> ctd'	<b>B2</b> <b>BE01</b> ctd'	<b>B3</b> <b>A111</b> ctd'
15:40 – 16:00	Coffee Break		
16:00 – 16:30	<b>P2a: Reports from the Breakout Sessions</b>		
16:30 – 18:00	<b>P2b: The Space Agencies: Programs and Boundary Conditions</b>		
19:00 – 21:00	No-Host Dinner		

## Charge to the Breakout Sessions

**B1: Mission requirements**

*Co-chairs: Bert Vermeersen, Victor Zlotnicki*

**3<sup>rd</sup> floor**

**A306**

**B2: Mission design**

*Co-chairs: Jürgen Müller, Stefano Cesare, Nico Sneeuw*

**this room**

**BE01**

**B3: Data processing, modelling and interpretation**

*Co-chairs: Frank Flechtner, Srinivas Bettadpur*

**1<sup>st</sup> floor**

**A111**

- Contributions to roadmap
- Contributions to resolutions
- Contributions to declarations
- Contributions to workshop report

## Equipment

### B1: Mission requirements

*Co-chairs: Bert Vermeersen, Victor Zlotnicki*

**3<sup>rd</sup> floor**

**A306**

### B2: Mission design

*Co-chairs: Jürgen Müller, Stefano Cesare, Nico Sneeuw*

**this room**

**BE01**

### B3: Data processing, modelling and interpretation

*Co-chairs: Frank Flechtner, Srinivas Bettadpur*

**1<sup>st</sup> floor**

**A111**

All rooms are equipped with:

- fixed projector connected with presentation notebook
- mobile projector (optionally: e.g. for minutes)
- blackboard

